



Two Layered Wireless Security System for Highly Secured Indoor Locations

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ABSTRACT: This paper proposes a smart way of handling the Electronic Voting Machine (EVM) theft problem by having a wireless network based security and monitoring system using WPAN, RF signal strength, MEMS motion sensors and GSM technology. The proposed system consists of EVM units each equipped with a MEMS motion sensor forming a WPAN network based on star topology with the coordinator node acting as the central hub of the network. The coordinator node broadcasts a beacon that enquires the status of all EVM units. Any disturbance to an EVM unit in all three dimensions can be sensed via MEMS sensors and this information will be transmitted to the coordinator unit which will send the details via SMS to respective higher authority. Radio frequency grid is an innovative way to secure a space, when an intrusion occurs, the RF propagation environment changes, and thus the received RF signal strength and Eigen values changes. The coordinator node is able to recognize this RSSI change and alert through SMS. This is an innovative method that provides low cost intrusion detection without costly cameras or video processing systems. Hence there is a two layer security providing complete protection for an entire storage room even if it contains hundreds of EVM units.

KEYWORDS: Eigen value, Eigen vector, WPAN, MEMS, space-time signal

I. INTRODUCTION

In recent days, the deal of interest in security systems for residential and office usage is increasing, such as intruder detection and event detection. General intruder detection uses infrared sensors, video cameras, and so on. Infrared sensors detect an intruder via a few infrared rays that are emitted by a human body. Video cameras detect an intruder or an event via image processing technologies that extract an intruder from the input image and identify whether the intruder corresponds to the event of interest or not. However, information obtained from one sensor or camera is local. Therefore, in conventional systems, a wide-range observation requires the installation of sensors or cameras in many places. Furthermore the detection capability of conventional systems depends on the installation location and the number of sensors or cameras. Achieving high performance comes to high costs.

The aim is to develop an autonomous anti-theft system for Electronic Voting Machine storage room that immediately sends an SMS to government authorities if it finds anything fishy. A two layer security model is proposed here. One layer uses MEMS accelerometer sensor and the second layer is an innovative attempt to secure a place which is sensor less and detects intrusion using wireless wave propagation and signal strength alone. The entire system uses IEEE 802.15.4, RF signal strength, MEMS motion sensors and GSM technology.

An electrical wave-based security system is reported in [4],[5] where an event such as intrusion is detected based on the change of received signal strength (RSS). Electrical waves arrive every corner, and thus wide sensing range is expected. The electrical wave-based security system has no need to be worried about privacy invasion by images. However, RSS suffers from the effects of noise and fluctuates even in static conditions. Thus, a detection error occurs. In this paper, we explain our wireless security and monitoring system based on space-time signal processing. The proposed system monitors a whole room with only a pair of transmitter and receiver. The receiver uses an antenna array. By using space-time signal processing, we get not only RSS that is susceptible to noise but also eigenvector spanning signal subspace that is inherent to its environment. When an event (e.g. a person intrudes into a house) occurs, the propagation environment changes, and thus the eigenvector changes. To detect an event, we use this change. In addition to security, the proposed system can be used as a monitoring system that can monitor people without invading their privacies by images. We show some experimental results and some interesting applications.



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II. LITERATURE REVIEW

Wireless Security and Monitoring System Using Array Antenna: Array Sensor

This paper [1] proposed wireless security and monitoring system using array antenna, referred to as array sensor. The proposed system exploits an antenna array on the receiver side and decomposes received signals into eigenvectors and eigenvalues. When an event (e.g. intrusion) occurs, the propagation environment changes, and thus the eigenvector changes. Based on the change of eigenvector, we can detect an event accurately. This paper introduces the fundamental principle of the proposed system and its various applications.

Wireless Security and Monitoring System Based on Space-Time Signal Processing

This paper [2] proposed wireless security and monitoring system based on space-time signal processing. The proposed system monitors a whole room with only a pair of transmitter and receiver. Using an antenna array at the receiver, it can get not only received signal strength (RSS) that is susceptible to noise but also eigenvector spanning signal subspace that is inherent to its environment. When an event (e.g. intrusion) occurs, the propagation environment changes, and thus the eigenvector changes. Based on the change of eigenvector, we detect an event.

Indoor human detection systems using VHF-FM and UHF-TV broadcasting waves

This paper [3] studies new indoor human detection systems using VHF-FM and UHF-TV broadcasting waves. By use of the broadcasting waves as radio transmission waves, the proposed systems don't need a transmitter; the systems are composed of only receiving systems including a receiving antenna and a receiver. The proposed systems can detect the presence or absence of human in a room, based on the principle that the received levels are fluctuated due to multi-path fading or shadowing with human presence.

Indoor Event Detection with Signal Subspace Spanned by Eigenvector for Home or Office Security

This paper [4] proposed an indoor event detection scheme using an electric wave such as intrusion into home or office. The proposed system exploits an antenna array on the receiver side and detects events such as intrusion using signal subspace spanned by eigenvector obtained by the antenna array. The eigenvector is not based on received signal strengths (RSS) but on the direction of arrival (DOA) of incident signals on an antenna array.

Signal-Subspace-Partition Event Filtering for Eigenvector-Based Security system Using Radio Waves

This paper [5] proposed signal-subspace-partition event filtering for the event detection system with signal subspace spanned by eigenvector in [3][4]. To detect an event with small changes of signal subspace components, we emphasize the changes of signal subspace components by selecting an appropriate component of signal subspace with signal-subspace partition. In addition, to detect an event in the presence of the changes of signal subspace components due to some undesired movements,

Experimental study of antenna arrays in indoor wireless applications

In this paper [6] array antenna based localization using spatial smoothing processing (SSP) is proposed for wireless security and monitoring, referred to as array sensor. The proposed method is based on the array sensor that exploits an array antenna at the receiver to detect the propagation environment of interest. If an event occurs, e.g., human motion, the propagation environment is changed. Thus the eigenvector and eigenvalue spanning the signal subspace that is inherent to its environment changes as well. The proposed method is improved from our previous work which uses only a limited number of signal subspace features.

III. PROPOSED SYSTEM

A. Proposed Model

The proposed system consists of EVM units each equipped with a MEMS motion sensor forming a WPAN network based on star topology with the coordinator node acting as the central hub of the network. The coordinator node broadcasts a beacon that enquires the status of all EVM units. Any disturbance to an EVM unit in all three dimensions can be sensed via MEMS sensors and this information will be transmitted to the coordinator unit which will send the details via SMS to respective higher authority.

The proposed system monitors a whole room with only a pair of transmitter and receiver. The receiver uses an antenna array. By using space-time signal processing, we get not only RSS that is susceptible to noise but also eigenvector spanning signal subspace that is inherent to its environment. When an event (e.g. a person intrudes into

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a house) occurs, the propagation environment changes, and thus the eigenvector changes. To detect an event, we use this change. In addition to security, the proposed system can be used as a monitoring system that can monitor people without invading their privacies by images. All data packets adhere to IEEE 802.15.4 frame format and each node has a transceiver circuitry to handle the packet reception and transmission. All EVM units have a low power microcontroller which runs the security algorithm

B. Methodology

The signal subspace spanned by eigenvector changes only when the environment of interest changes. In this section, we explain our proposed wireless security and monitoring system using signal subspace spanned by eigenvector. The proposed system uses the subspace method. The subspace method analyzes the radio wave propagation by focusing on the property of eigenvectors and eigenvalues obtained by the eigenvalue decomposition (EVD) of correlation matrix of received signals. The correlation matrix is divided into signal subspace and noise subspace, and both subspaces are orthogonal. We use the signal subspace spanned by the first eigenvector. The incident multipath signals go through everywhere of interest. Thus, the signal subspace spanned by eigenvector represents wave propagation. When the environment of interest changes, the wave propagation changes and thus the signal subspace spanned by eigenvector

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$$P_{vec}(t) = \left| \mathbf{v}_{no}^H \mathbf{v}_{ob}(t) \right|$$

Where \mathbf{v}_{no} is the reference eigenvector obtained when no event occurs and $\mathbf{v}_{ob(t)}$ is the eigenvector obtained when we observe the environment of interest. Both vectors are normalized to one. Then, $P_{vec(t)}$ is close to 1 because $\mathbf{v}_{ob(t)}$ is close to \mathbf{v}_{no} when no event occurs, and lower than one when some events occur.

C. Block Diagram

The fig.1 shows the block diagram of the proposed system. It has a central monitoring mote and the electronic voting machine mote

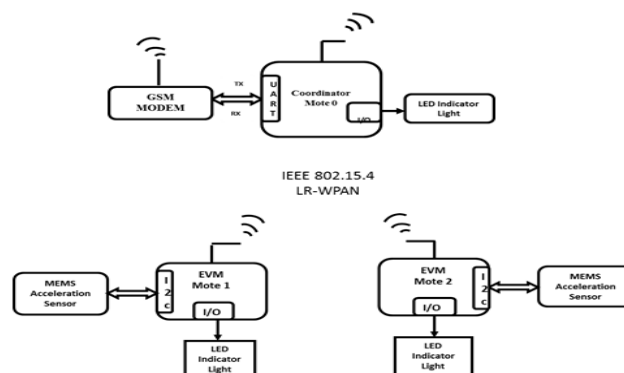


Fig.1 Block Diagram

D. Electronic Voting Machine

The fig.2 shows the circuit diagram of the Electronic Voting Machine mote. It has a controller along with a PCB antenna and the MEMS accelerometer.

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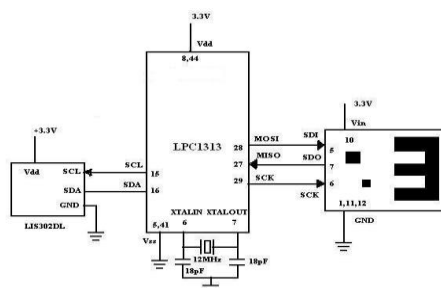


Fig.2 Electronic Voting Machine Mote

E. Central Monitoring Mote

The fig.3 shows the Central Monitoring Mote. It has the controller connected with the PCB antenna and GSM module.

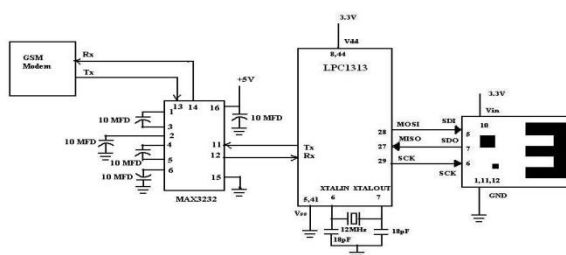


Fig.3 Central Monitoring Mote

IV. EXPERIMENTAL RESULT

A. Experimental Setting

The fig.3 shows the proposed system. It has a central monitoring mote and the two electronic voting machine motes.

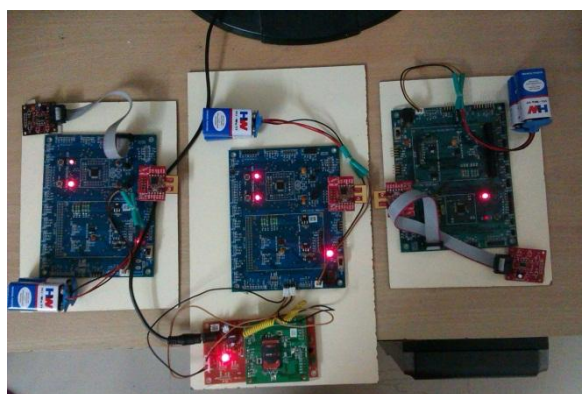


Fig.4 Proposed System

B. Experiment 1: Communication Between Motes: Hand Shaking

The fig. 5 shows the hand shaking between the motes. It describe the communication between the motes using the Zena™ packet sniffer. All data packets adhere to IEEE 802.15.4 frame format and each node has a transceiver circuitry to handle the packet reception and transmission.



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Frame	Time(s)	Len	MAC Frame Control	Seq	Dest	Destination Address	Source Address	Connection Request	Capability Info
00001	+10058096	26	Type Sec Pend ACK IPAN CMD N N Y Y	Seq HAM PAN 0x0A	Dest PAN 0x120E	Destination Address 0x1122334455660E01	Source Address 0x1122334455660E00	Channel 0x00	Sec Sync Req N N Y
00002	+1568	5	Type Sec Pend ACK IPAN ACK N N N N	Seq HAM RSSI Corr CRC 0x0A	Dest PAN 0x120E	Destination Address 0x1122334455660E01	Source Address 0x1122334455660E00	Channel 0x00	Sec Sync Req N N Y
00003	+10064048	26	Type Sec Pend ACK IPAN CMD N N Y Y	Seq HAM PAN 0x0A	Dest PAN 0x120E	Destination Address 0x1122334455660E01	Source Address 0x1122334455660E00	Channel 0x00	Sec Sync Req N N Y
00004	+1568	5	Type Sec Pend ACK IPAN ACK N N N N	Seq HAM RSSI Corr CRC 0x0A	Dest PAN 0x120E	Destination Address 0x1122334455660E01	Source Address 0x1122334455660E00	Channel 0x00	Sec Sync Req N N Y
00005	+94464	26	Type Sec Pend ACK IPAN CMD N N Y Y	Seq HAM PAN 0x0B	Dest PAN 0x120E	Destination Address 0x1122334455660E02	Source Address 0x1122334455660E00	Channel 0x00	Sec Sync Req N N Y
00006	+11041648	5	Type Sec Pend ACK IPAN ACK N N N N	Seq HAM RSSI Corr CRC 0x0B	Dest PAN 0x120E	Destination Address 0x1122334455660E02	Source Address 0x1122334455660E00	Channel 0x00	Sec Sync Req N N Y
00007	+5744	26	Type Sec Pend ACK IPAN CMD N N Y Y	Seq HAM PAN 0x0A	Dest PAN 0x120E	Destination Address 0x1122334455660E01	Source Address 0x1122334455660E00	Channel 0x00	Sec Sync Req N N Y
00008	+1568	5	Type Sec Pend ACK IPAN ACK N N N N	Seq HAM RSSI Corr CRC 0x0A	Dest PAN 0x120E	Destination Address 0x1122334455660E01	Source Address 0x1122334455660E00	Channel 0x00	Sec Sync Req N N Y
00009	+12072000	18	Type Sec Pend ACK IPAN DATA N N N Y	Seq HAM PAN 0x0C	Dest PAN Addr 0x0C	Destination Address 0x1122334455660E00	Source Address 0x1122334455660E00	Channel 0x00	Sec Sync Req N N Y
00010	+1051696	18	Type Sec Pend ACK IPAN DATA N N Y Y	Seq HAM PAN 0x0E	Dest PAN Addr 0x0E	Destination Address 0x1122334455660E00	Source Address 0x1122334455660E00	Channel 0x00	Sec Sync Req N N Y
00011	+1048464	18	Type Sec Pend ACK IPAN DATA N N N Y	Seq HAM PAN 0x0E	Dest PAN Addr 0x0E	Destination Address 0x1122334455660E00	Source Address 0x1122334455660E00	Channel 0x00	Sec Sync Req N N Y
00012	+1048128	18	Type Sec Pend ACK IPAN DATA N N N Y	Seq HAM PAN 0x0F	Dest PAN Addr 0x0F	Destination Address 0x1122334455660E00	Source Address 0x1122334455660E00	Channel 0x00	Sec Sync Req N N Y
00013	+15221264	18	Type Sec Pend ACK IPAN DATA N N N Y	Seq HAM PAN 0x0F	Dest PAN Addr 0x0F	Destination Address 0x1122334455660E00	Source Address 0x1122334455660E00	Channel 0x00	Sec Sync Req N N Y

Fig.5 Communication between Motes (Handshaking)

C. Experiment 2: Detection of Person Intrusion

Figure 6 shows experimental results for the person intruding, stopping, or moving. In this experiment, the person opens the door and intrudes, and passes through A, B, C, and goes through the door. The person stops for 20 seconds at each point, A, B, C. The cost function $P_{vec}(t)$ changes significantly when the door opens. $P_{vec}(t)$ also fluctuates significantly when the person moves and fluctuates moderately when the person stops. These are because the change of environment, such as the door opening, the existence of the person, and the person's motion, changes the propagation of the radio waves and thus the first eigenvector as well. Therefore, the cost function that is the correlation of the first eigenvector between in the reference and in the observation, also changes. As a result, we can easily detect the person's movement, intruding, stopping or moving. Moreover, we can see that four elements are enough to detect static or dynamic state in this environment, and thus the receiver can be more simplified.

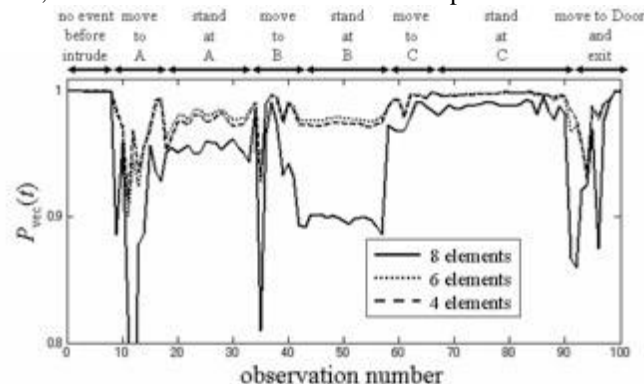


Fig.6 Detection performance of person's behaviours, intrusion, walking, and stopping

Fig. 7 shows the detection of the person intrusion using the Zena™ packet sniffer. When a person intruded the RSSI value changes and so the eigen value and vector changes.



Frame	Time(us)	Len	MAC Frame Control	Type	Seq	Dest PAN	Dest Addr	Source Address	Payload	RSSI	Corr	CRC
00039	+1048964	18	Type Sec Pend ACK IPAN	N	N	0x2A	0x120E	0x122334455660E00	0x00	-13	0x6A	OK
00040	+1051728	18	Type Sec Pend ACK IPAN	N	N	0x2B	0x120E	0x122334455660E00	0x00	-15	0x6A	OK
00041	+44615352	18	Type Sec Pend ACK IPAN	N	N	0x2C	0x120E	0x122334455660E00	0x00	-16	0x6B	OK
00042	+1049424	18	Type Sec Pend ACK IPAN	N	N	0x2D	0x120E	0x122334455660E00	0x00	-16	0x6B	OK
00043	+1049556	18	Type Sec Pend ACK IPAN	N	N	0x2E	0x120E	0x122334455660E00	0x00	-15	0x6B	OK
00044	+1049688	18	Type Sec Pend ACK IPAN	N	N	0x2F	0x120E	0x122334455660E00	0x00	-15	0x6B	OK
00045	+1051568	18	Type Sec Pend ACK IPAN	N	N	0x30	0x120E	0x122334455660E00	0x00	-14	0x6A	OK
00046	+45984432	18	Type Sec Pend ACK IPAN	N	N	0x31	0x120E	0x122334455660E00	0x00	-14	0x69	OK
00047	+1049440	18	Type Sec Pend ACK IPAN	N	N	0x32	0x120E	0x122334455660E00	0x00	-14	0x6A	OK
00048	+1050932	18	Type Sec Pend ACK IPAN	N	N	0x33	0x120E	0x122334455660E00	0x00	-13	0x6B	OK
00049	+53012640	24	Type Sec Pend ACK IPAN	N	N	0x0B	0x120E	0x11223334455660E00	0x02	-13	0x68	OK
00050	+1472	5	Type Sec Pend ACK IPAN	N	N	0x0D				-14	0x69	OK

Fig.7 Detection of Person Intrusion

D. Experiment 3: Detection of Electronic Voting Machine Movement

Figure 8 shows experimental results for the Electronic Voting Machine Movement. In this experiment, the person opens the door and steals the EVM on the point D shown in Fig. 6. $P_{vec(t)}$ does not fluctuate while no event occurs whether there is the EVM or not. However, the value of $P_{vec(t)}$ after the EVM movement is different from that before the EVM movement. This is because the environment in the room (i.e. radiopropagation) changes owing to the EVM movement. Thus, the first eigenvector also changes and the correlation becomes lower. Therefore, the proposed system has a possibility to detect something stolen and something left behind. The detection performance, such as size, material, and place that the proposed system can detect depends on the signal that the proposed system uses, such as radio frequency and bandwidth of the signal.

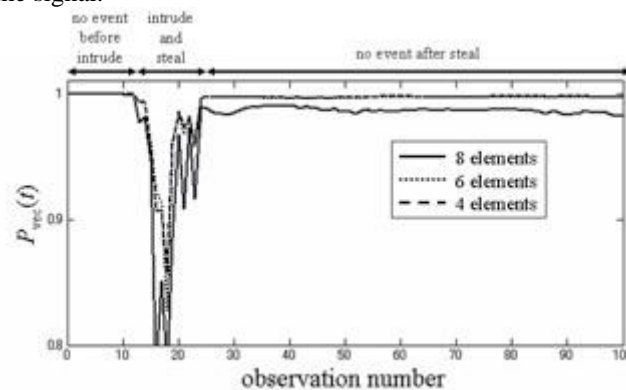


Fig. 8 Detection performance of EVM Movement

The fig. 9 shows the detection of the EVM movement using the Zena™ packet sniffer. The RSSI value changes and the eigen values are different from that before the movement of the EVM unit.



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Frame	Time(s)	Len	MAC Frame Control	Seq	Dest	Dest	Source Address	Payload	FCS
00073	13.048944	18	Type Sec Psend ACK IPAN DATA N N N Y	Hum	PAH	Addr	0x1122334455660E00	0x00	RSBI Corr CRC -17 0x6B OK
00074	13.049520	18	Type Sec Psend ACK IPAN DATA N N N Y	Hum	PAH	Addr	0x1122334455660E00	0x00	RSBI Corr CRC -16 0x6B OK
00075	13.049220	18	Type Sec Psend ACK IPAN DATA N N N Y	Hum	PAH	Addr	0x1122334455660E00	0x00	RSBI Corr CRC -16 0x65 OK
00076	13.048944	18	Type Sec Psend ACK IPAN DATA N N N Y	Hum	PAH	Addr	0x1122334455660E00	0x00	RSBI Corr CRC -15 0x63 OK
00077	13.048916	18	Type Sec Psend ACK IPAN DATA N N N Y	Hum	PAH	Addr	0x1122334455660E00	0x00	RSBI Corr CRC -17 0x6A OK
00078	13.048120	18	Type Sec Psend ACK IPAN DATA N N N Y	Hum	PAH	Addr	0x1122334455660E00	0x00	RSBI Corr CRC -15 0x68 OK
00079	13.048736	18	Type Sec Psend ACK IPAN DATA N N N Y	Hum	PAH	Addr	0x1122334455660E00	0x00	RSBI Corr CRC -18 0x6B OK
00080	13.047888	18	Type Sec Psend ACK IPAN DATA N N N Y	Hum	PAH	Addr	0x1122334455660E00	0x00	RSBI Corr CRC -17 0x6B OK
00081	13.048720	18	Type Sec Psend ACK IPAN DATA N N N Y	Hum	PAH	Addr	0x1122334455660E00	0x00	RSBI Corr CRC -09 0x6B OK
00082	13.052224	18	Type Sec Psend ACK IPAN DATA N N N Y	Hum	PAH	Addr	0x1122334455660E00	0x00	RSBI Corr CRC -18 0x6B OK
00083	13.048264	24	Type Sec Psend ACK IPAN DATA N N N Y	Hum	PAH	Addr	0x1122334455660E00	0x01	RSBI Corr CRC -17 0x6B OK
00084	13.472	18	Type Sec Psend ACK IPAN ACK N N N N	Hum	PAH	Addr	0x1122334455660E00	0x00	RSBI Corr CRC -16 0x65 OK

Fig.9 Detection of EVM Movement

V. CONCLUSION

The proposed security system is a two Layer security model which provides autonomous and intelligent operation. Human securities are minimized and there is no need of costly cameras and other video or image processing technologies. All the nodes are battery powered. The proposed system can be useful for monitoring without invading privacy, such as monitoring elderly person living alone, monitoring person in bathroom. There are various applications for the proposed system other than already mentioned. One interesting application is a car security system that monitors a car while parking. The proposed system can detect not only intrusion into a car or movement of a car but also suspicious behaviours, such as looking into a car.. More results will be reported in the near future.

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