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## Wireless Temperature Monitoring System Using Microcontroller

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**ABSTRACT:** To get rid of the problem of Obscurity to control temperature in industries, a microcontroller based controller has been proposed. A temperature sensor has been used to measure the temperature of the room and the speed of the fan is varied according to the room temperature using pulse width modulation technique. We have used AT89C51 microcontroller kit for interfacing our system. This paper is about controlling various DC fan speed devices using PWM which is working on Radio frequency. Let us take example if we can connect the DC fan at the output then we can switch on or off of fan at a desired speed using the PWM technique and the status of various devices is displayed on LCD. In this paper we are using RF transmission because with the help of IR transmitter there is a problem of directivity and range of working, that problem is eliminated with RF transmission. RF has better directivity and frequency range.

**KEYWORDS:** Microcontroller, LCD, Reception, Transmission, Wireless

### I. INTRODUCTION

The goal of the paper is to achieve intelligent device control and secure environmental working conditions by interfacing various sensors and devices to the AT89C51 microcontroller and RF modules with the Atmel controller for data transmission respectively. Wireless based industrial automation is a prime concern in our day-to-day life. Industrial automations depend on the power systems and which requires distance control and regulated systems. Wireless Control Networks (WCNs) have revolutionized the design of emerging embedded systems and triggered a new set of potential applications. In addition to building automation, environmental surveillance, or military operations, industrial automation is also expected to greatly benefit from WSNs in terms of faster installation and maintenance, cost savings, and easier plant reconfiguration. RF is an emerging short-range, low rate wireless network technology. RF also presents some potentially interesting features for supporting large-scale ubiquitous computing applications, namely power efficiency, timeliness and scalability. In managing the move to wireless, it is clear that common wireless protocols such as Wi-Fi and Bluetooth can be utilized on the factory floor. The challenge is to understand how to utilize wireless solutions, developed for IT applications, as replacements for wired systems in time-critical scenarios typical of factory floor domains. To date, most wireless systems in production systems are focused on applications that require polling frequencies on the order of seconds or longer. Standardization of technology again plays an important role for globalization of these profiled developments.

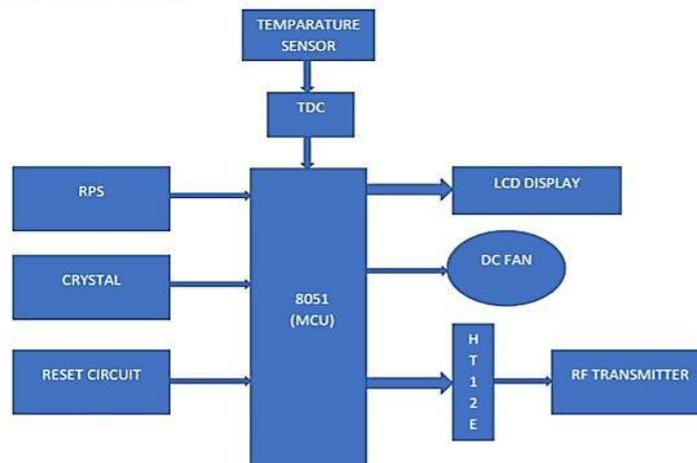
### II. RELATED WORK

The microcontrollers are user friendly and can be operated by anybody without any trouble. Also less manual intervention is required for operating the microcontrollers, which reduces labor [2] cost. Here the clock source is coming from the crystal of microcontroller [6]. DC motors are widely used because its speed-torque characteristics can be varied to almost any useful form [3, 4]. There are so many ways to control speed. For instance, armature voltage control and excitation control method [7]. Pulse width modulation is a method for binary signals generation, which has 2 signal periods (high and low). The width (W) of each pulse varies between 0 and the period (T) [11, 12]. The main principle is control of power by varying the duty cycle [13].

### III. SYSTEM ARCHITECTURE

This block diagram contains the wireless transmitter section. This section has microcontroller as a transmitter module, temperature sensor LM 35, ADC 0809. Each and every module in the transmitter section will be controlled by the Microcontroller. The Temperature sensor LM35 senses the temperature as an analog signal, by the use of ADC 0809 these analog signals will be converted to digital and it will be transferred to the microcontroller. Microcontroller processes that digital signal and then transmits the digital signal through the Wireless Transmitter module as an analog signal [6]. ADC-0809 has an inbuilt 8-channel multiplexer. It performs simultaneously A/D conversion of more than one analog signal. When the unknown analog input equals the reference voltage, the internal comparator output allows the digital output to become available at the output of the 8-bit latch. The characteristics of reference voltage is as shown in graph no.1. While the process of A/D conversion is initiated by a positive pulse at the terminal marked “START OF CONVERSION” the A/D converter produces the pulse at the terminal marked “END OF THE CONVERSION”. This pulse is used to inform the microcontroller that the cycle of A/D conversion has been completed.

#### TRANSMITTER SECTION:



#### RECEIVER SECTION:

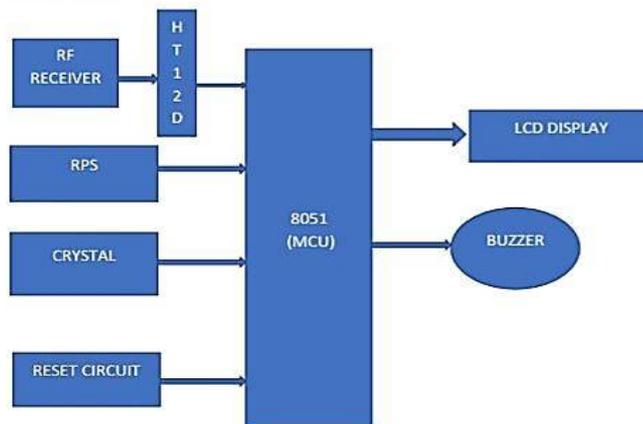


Figure 1: Block diagrams of proposed system

**Atmel AT89C51:** The on-chip Flash allows the program memory to be reprogrammed in-system or by a conventional nonvolatile memory programmer. By combining a versatile 8-bit CPU with Flash on a monolithic chip, the Atmel



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AT89C51 is a powerful microcomputer which provides a highly-flexible and cost-effective solution to many embedded control applications.

**LM35:** LM35 is a device which converts the physical signal into electrical signal. That's why this is known as the transducer. It is calibrated with the environmental temperature and it is linearly varies with the temperature and its output is in volt. There is no need of external calibration to provide the accuracy of the LM35 at room temperature which is about  $\pm 1/4^{\circ}\text{C}$ . Minimum temperature that can be measured by the LM35 device is  $-55^{\circ}\text{C}$ . And maximum temperature that can be measured by LM35 is  $150^{\circ}\text{C}$ . Calibration of LM35 is done by trimming at the water level. To make the interfacing of control circuitry and readout circuitry very easy, low impedance at output side, output which is linear and precise inherent calibration of LM35 plays an important role. Temperature sensor takes a very low current of order  $60\ \mu\text{A}$  from the input supply. Heat loss in the LM35 is very less degree of around  $0.1^{\circ}\text{C}$ . LM35 can work in the range of  $-50^{\circ}\text{C}$  to  $+150^{\circ}$  which is the rated value. Another device which is also a temperature sensor of the family of LM35 known as LM35C which ranges from  $-40^{\circ}\text{C}$  to  $+110^{\circ}\text{C}$ . LM35 costs around 10 rupees in India and is easily available in the market which anyone can buy at any convenience store or electronics store.

**RF Transmitter/ receiver (RX-434) modules:** The RF receiver (RX-434) module can receive the signal transmitted by the transmitter from a distance up to 1 to 1.5 km. The range can be increased up to 30 meters using a good antenna.  $D_{\text{out}}$  pin of RX-434 RF Module is connected to  $D_{\text{in}}$  pin of Decoder IC HT12D (IC 4).  $D_{\text{in}}$  pin of IC 4 receiver address and data bits serially from the RF Module. Decoder IC 4 separate data and address from the received information. It accepts data only if the received address matches with address assigned to Encoder IC 1 (HT12E). We have used '1111' as the permanent address for communication. Pins 1 through 8 of IC 4 are address pins and therefore 256 possible addresses are available. The address on the Encoder and Decoder ICs must match for the data to be valid.

The HT12D decoder receives serial address and data from the Encoder continuously with its local addresses. If no error or unmatched codes are found, the input data codes are decoded and transferred to the output pins. VT pin (valid transmission) goes high to indicate a valid transmission. The HT12D provides four latch type data pins whose data remains unchanged until new data is received.

**Transformer:** It converts alternating current from one value to other value of voltage with a limited loss of power. Step-up transformers have more winding towards the secondary section compared to primary section. This in turn increases the value of voltage. Step-down transformers have less winding towards the secondary section compared to that with the primary section. This in turn decreases the value of voltage. The step down transformer is used commonly in power supplies to reduce the high risk associated with high voltage to considerably low voltage. The transformer has two coils namely primary coil and secondary coil. Between these two coils there is no electrical connection rather they are connected by the alternating magnetic field. This field is created by using soft-iron core of the transformer.



Figure 2: Transformer

**Bridge rectifier:** An electric device which periodically reverses the direction that is from alternating current to direct current is rectifier. The output voltage from transformer is given as input to bridge rectifier. That converts alternating current into direct current which is pulsating.

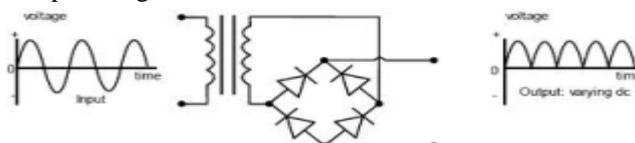


Figure 3: Bridge rectifier

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**Filter:** Capacitive filter is used in this project. It removes the ripples from the output of rectifier and smoothens the D.C. Output received from this filter is constant until the mains voltage and load is maintained constant. However, if either of the two is varied, D.C. voltage received at this point changes. Therefore a regulator is applied at the output stage.

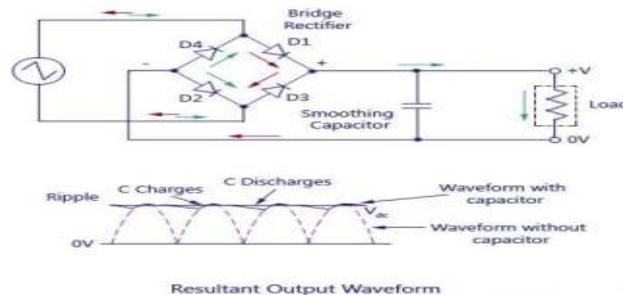


Figure 4: Filter

1. Keil software for Microcontroller programming.
2. Flash magic software for Microcontroller burning.
3. Diptrace Software for PCB Layout.
4. Language: Embedded C Assembly.

## IV. RESULTS AND DISCUSSION

The logical representation of the software code has been presented in the flowchart form. Figure 4 shows the flowchart of the logic implemented in the modeled system.

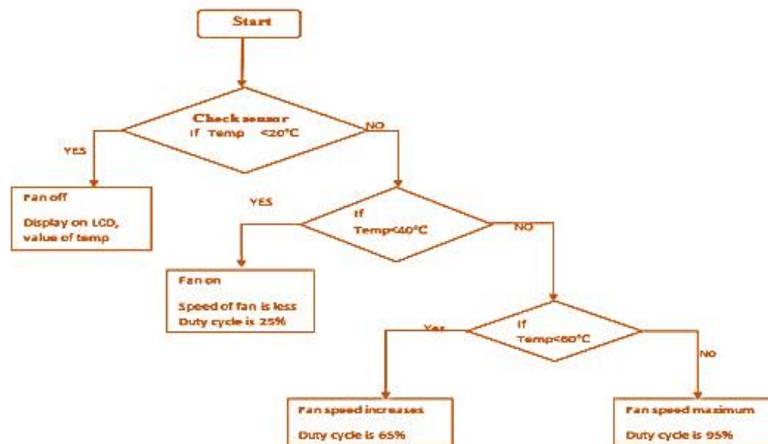


Fig 4 Flow chart

The temperature is read from the temperature sensor and the condition is checked and the following processes are done:

- 1) When temperature is greater than zero and less than 20 degree Celsius, the fan is OFF.
- 2) When temperature is greater than 20 and less than 40 degree Celsius, the fan speed is SLOW.
- 3) When temperature is greater than 40 and less than 60 degree Celsius, the fan speed is MEDIUM.
- 4) When temperature is greater than 60, the fan speed is FAST

## V. CONCLUSION & FUTURE SCOPE

The microcontroller based totally automated speed control of fan primarily based on room temperature the use of PWM approach has been proposed on this paper. The speed of fan relies upon on the room temperature and there is no need



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for regulating the speed manually. Various graphs were plotted to show the various relationships between different parameters. PWM technique is discovered to be suitable for controlling fan speed in keeping with room temperature. After evaluating duty cycle and speed of DC Fan in line with temperature variation. In this design, the RF provide low power consumption, low cost and easy RF communication to permit remote control and present day size of business retailers which will shop strength. RF era is suitable for the utility in strength monitoring device. It can provide reliable security for the operation of electrical energy structures. The machine is small, simple, and cost effective and desirable for RF control of device.

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