



Design of Boost Converter with Fuzzy Logic Controller for Renewable Energy Sources

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ABSTRACT: Due to the lack of conventional energy sources, world is moving towards renewable energy sources as an alternative for the energy needs. As these are pollution free and cheap, these are very useful. Fuel Cell energy and solar energy are examples of renewable energy sources which give a small amount of DC voltage as output. To increase this voltage level, Boost converter is designed. This Boost Converter is best suited for applications where load is 100 Ω . Fuzzy Logic Controller is used to control the duty ratio of Boost Converter. Results of Fuzzy Logic Controlled Boost Converter is compared with conventional PI controlled Boost Converter.

KEYWORDS: Boost Converter, proportional Integral Controller (PI), Fuzzy Logic Controller.

I.INTRODUCTION

As the population of world is increasing the requirement of energy is also increasing resulting in “Energy Crisis” [1]. To overcome this energy crisis world is moving towards the renewable sources of energy like solar, wind, biomass and geothermal etc. All these sources are green sources as these are combustion free hence gives promise to clean source of energy. But the output of solar cell and fuel cell is DC voltage and its amount is so small that cannot be used for practical applications [5]. To overcome this problem, Boost Converter is used to increase the DC voltage. Boost converter increases the DC voltage to the acceptable level for use in different applications. Wherever AC signal is required, the output of Boost Converter is fed to the inverter and this AC signal is used for different applications.

II.BOOST CONVERTER

DC/DC boost converter is a power device which gives a constant high DC-voltage as output in spite of a varying DC-voltage on the input. Primarily, boost converter consists of two semiconductor devices a diode and a switching device (IGBT, MOSFET, Thyristor etc.) and energy storage elements, a capacitor and an inductor. Filter made of capacitor is normally added to the output of the converter to reduce output voltage ripple. The input-output voltage ratio is controlled by the switching duty cycle D of the switching device. The value of duty ratio D lies between 0 and 1. The boost converter has a non-linear relationship between duty cycle and input-output voltage ratio. The output of the boost converter is given as follows.

$$V = \frac{V_s}{1-D} \quad (1)$$

$$D = \frac{T_{on}}{T} \quad (2)$$

$$T = T_{on} + T_{off} \quad (3)$$

Functional diagram of typical boost converter is shown in fig. 1.

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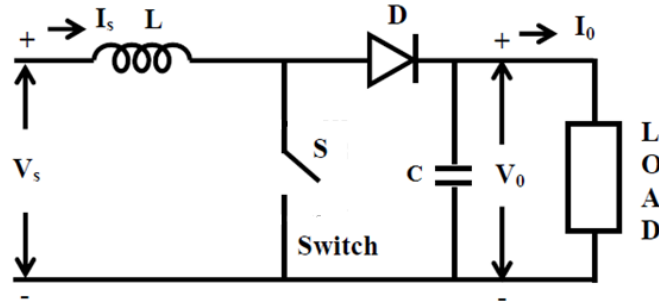


Fig. 1 Functional Diagram of Boost Converter

BASIC PRINCIPLE

The principle behind the boost converter is the ability of an inductor to resist changes in current by generating a magnetic field. Working of the boost converter can be explained from the following points.

- (i) ON State: - In this state the switch is ON which results an increase in inductor current and current does not pass through diode D, Capacitor C and Load. On state is shown in the following Fig. 2.

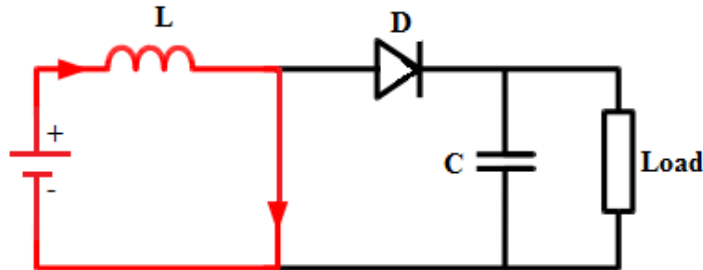


Fig. 2 Boost Converter in ON State

- (ii) OFF State: - In this state, the switch is OFF and the path of inductor current is through the freewheeling diode D, the capacitor C and the load R. This results in transferring the stored energy during the ON state to the capacitor.

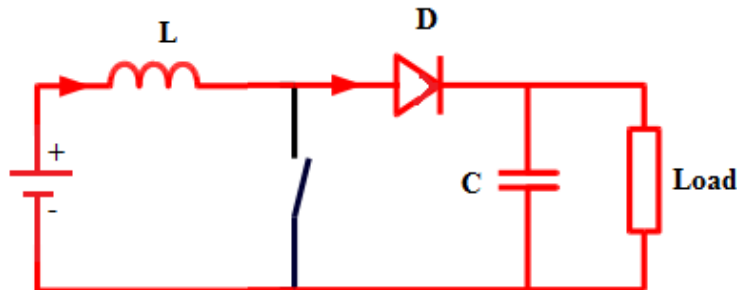


Fig. 3 Boost Converter in OFF State

The switching of switching device is maintained fast, so the inductor will not discharge fully in between charging stages, and when the switch is open the input source alone will provide a voltage greater than its value to load. Also the capacitor in parallel with the load will be charged to this additional voltage. Now when the switch is closed, the capacitor will be able to provide the voltage and energy to the load. During this time, the blocking diode will prevent

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the capacitor from discharging. The switch has to be opened again fast enough to prevent the capacitor from discharging too much.

The parameters of designed Boost converter are shown in the following table I.

Table I Parameter of Boost Converter

| Parameter | V _{in} (V) | L (mH) | C (μF) | Load (Ω) |
|-----------|---------------------|--------|--------|----------|
| Value | 17 | 100 | 100 | 100 |

Error signal generated from comparison of desired output and actual output is controlled by the controller. Output of this controller generates the switching pulses of the MOSFET (switch) of Boost Converter.

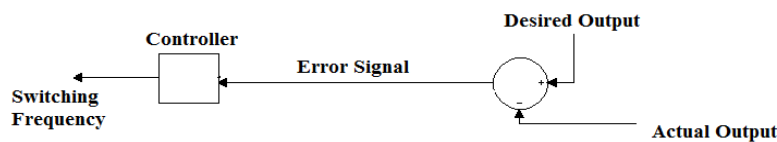


Fig. 4 Closed loop system of Boost Converter

Two controllers namely PI Controller and Fuzzy Logic controller are used for the purpose and results are compared.

III. PI CONTROLLER

PI controller is one of the most common types of controller used for the control purpose. It needs mathematical modeling of the system to compute the values of parameters k_p and k_i [2].

k_p is the parameter to adjust the value of proportional controller and k_i to control the value of integral controller.

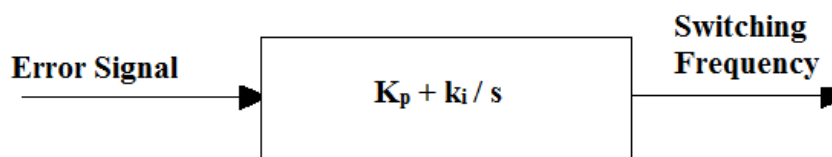


Fig. 5 PI controller

IV. FUZZY LOGIC CONTROLLER

Rules for fuzzy logic control are derived from the practical knowledge of behaviour of the system. It does not need mathematical calculation hence it is very easy to construct [3-4].

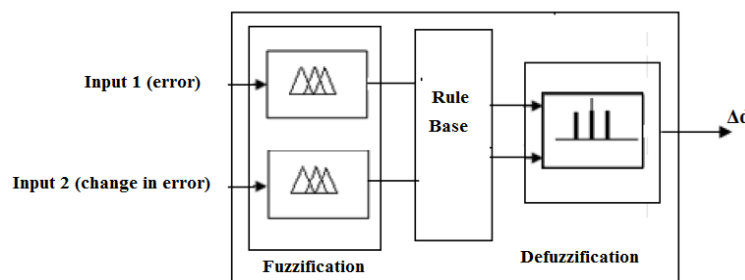


Fig. 6 Block Diagram of Fuzzy Logic Controller

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To implement the fuzzy based rule, error and change in error are taken as FIS variables [5-9].
Value of error and change in error are taken as follows.

$$e(n) = V_{out}(\text{desired}) - V_{out}(\text{actual}) \tag{4}$$

$$Ce(n) = e(n) - e(n-1) \tag{5}$$

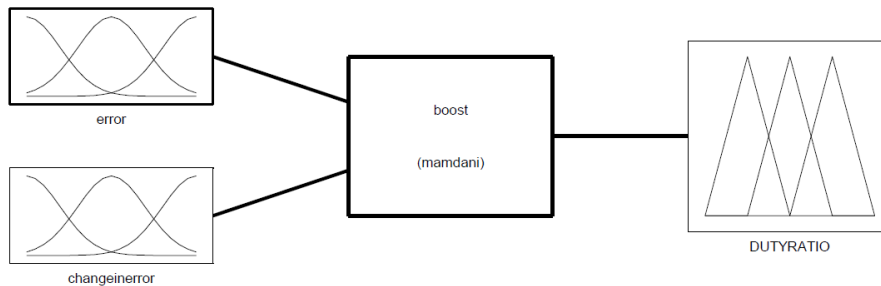


Fig. 7 FIS variables for Boost Converter

Mamdani triangular Membership function for the input variable “error” is defined as in following figure 8.

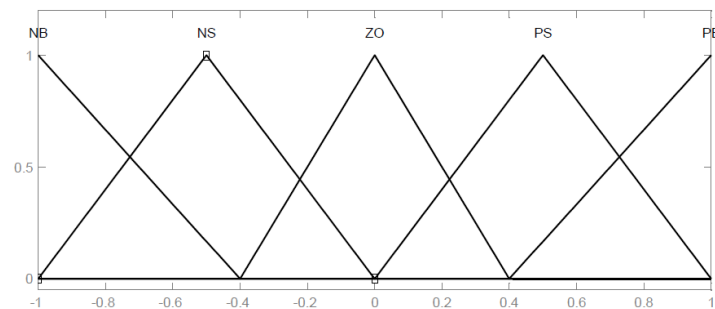


Fig. 8 Input Variable “Error”

Mamdani triangular Membership function for the input variable “change in error” is defined as in following figure 9.

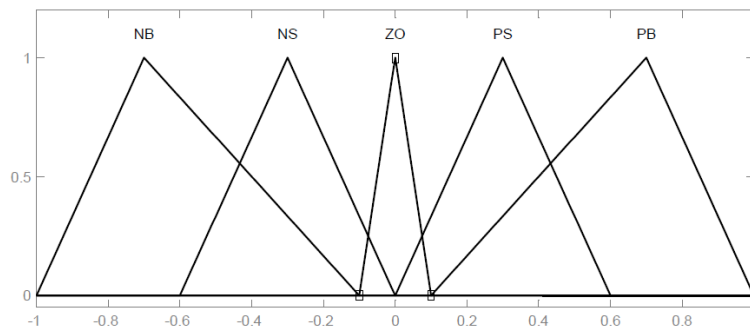


Fig. 9 Input Variable “change in error”

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Mamdani triangular Membership function for the output variable “duty ratio” is defined as in following figure 10.

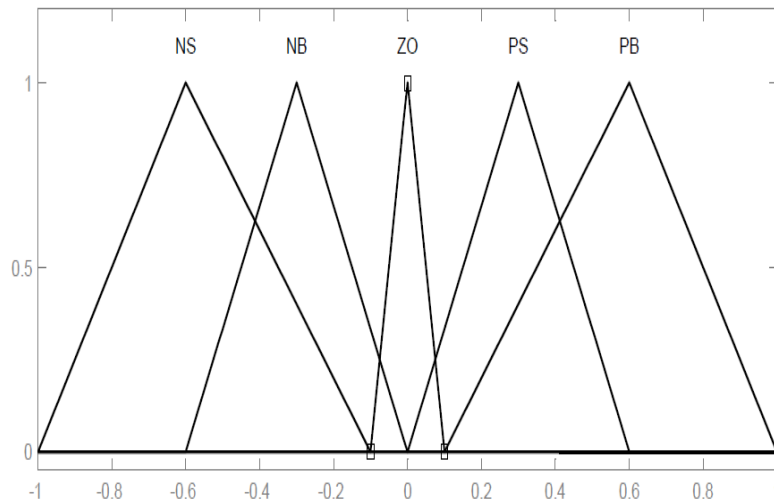


Fig. 10 Output Variable “Duty Ratio”

Rules for the Fuzzy Logic Controller are defined in the following table.

Table I

| e ce | NB | NS | Z | PS | PB |
|---------|----|----|----|----|----|
| NB | NB | NB | NB | NS | Z |
| NS | NB | NB | NS | Z | PS |
| Z | NB | NS | Z | PS | PB |
| PS | NS | Z | PS | PB | PB |
| PB | Z | PS | PB | PB | PB |

V. RESULT AND ANALYSIS

Result of Boost Converter with PI controller is shown in Fig. 11.

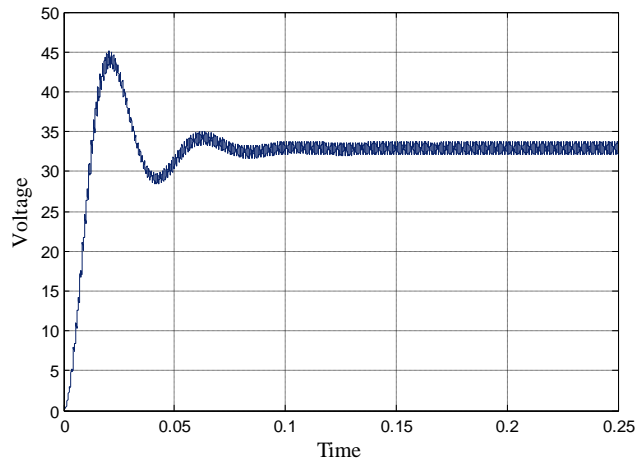


Fig. 11 output of Boost Converter (PI Controller)

Result of Boost Converter with Fuzzy Logic Controller is shown in Fig. 12.

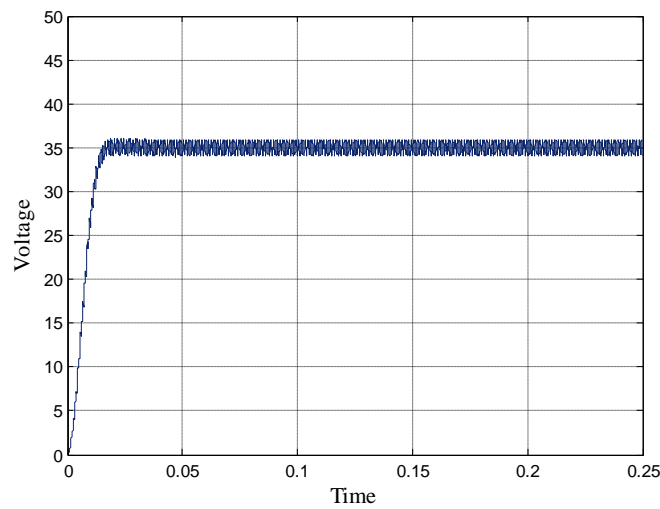


Fig. 12 Output of Boost Converter (Fuzzy Logic Controller)

Comparison of both the results is shown in the following table II.

Table II Comparison of Boost Converter output

| | PI Controller | Fuzzy Controller |
|----------------|---------------|------------------|
| Peak Overshoot | 45.0866 V | No Oscillations |
| Settling Time | 120 ms | 17 ms |



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VI.CONCLUSION

In this paper the boost converter is designed for the renewable energy sources like fuel cell, solar cell etc. The output of this source is fed to the Boost Converter to get required output for use in different application. Two types of controllers PI Controller and Fuzzy controller are used to control the output. With reference to Table I it is seen that Peak Overshoot of PI controller is 45.0866 V while output of Fuzzy Controller has no oscillations and with reference to Table II it is seen that settling time of PI controller is 120 ms while of Fuzzy Controller is 17 ms. So it can be said that Fuzzy controller is better than conventional PI controller.

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BIOGRAPHY



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